

**A newborn in the  $\lambda\delta$  family: introducing  $\lambda\delta$ -2B**

**Ferruccio Guidi**

**DISI, University of Bologna, Bologna, Italy**

**`ferruccio.guidi@unibo.it`**

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## 1. The $\lambda\delta$ family: design requirements

We designed the systems of the  $\lambda\delta$  family to meet the next features:

- predicative higher-order abstraction (de Bruijn unified binder  $\lambda$ );
- telescopic explicit substitution in terms (abbreviation  $\delta$ );
- type checking reduces to validation (type cast  $\odot$ );
- valid terms are typed (infinite type sequences are possible);
- small-step conversion (context-sensitive conversion);
- type construction and type conversion separated in type inference.
- infinite levels of terms (**no:**  $T$  or  $K$  are sorts if  $\Gamma \vdash M : T : K$ );
- relaxed typing (**no:**  $\Gamma$  is valid if  $\Gamma \vdash M : T$ );
- desirable invariants hold (confluence, normalization, preservation);
- the invariants are formally specified and machine-checked.

Our systems are outside both the Automath family and the PTS family.

## 2. Defining $\lambda\delta$ -2B (1 of 3)

**Morphology & syntax.** Alphabet:  $( ) . \star \# \textcircled{c} @ \lambda \delta \Lambda \Delta$  [integers:  $s, i$ ].

Terms:  $T, U, V, W := \star s \mid \#i \mid (\lambda W).T \mid (\delta V).T \mid (@V).T \mid (\textcircled{c}U).T$

Local environments:  $L, K := \star \mid K.(\Lambda W) \mid K.(\Delta V)$

**Reduction steps & type inference steps.** The function  $\uparrow_h$  is a parameter.

$$\text{(theta)} \quad L \vdash (@V).(\delta W).T \mapsto_{\theta} (\delta W).(@\uparrow^1 V).T$$

$$\text{(beta)} \quad L \vdash (@V).(\lambda W).T \mapsto_{\beta} (\delta(\textcircled{c}W).V).T$$

$$\text{(delta)} \quad K.(\Delta W) \vdash \#1 \mapsto_{\delta} \uparrow^1 W$$

$$\text{(zeta)} \quad L \vdash (\delta W).\uparrow^1 T \mapsto_{\zeta} T$$

$$\text{(epsilon)} \quad L \vdash (\textcircled{c}U).T \mapsto_{\epsilon} T$$

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$$\text{(ess)} \quad L \vdash \star s \mapsto_s \star \uparrow_h s \quad [\text{applies endlessly}]$$

$$\text{(ell)} \quad K.(\Lambda W) \vdash \#1 \mapsto_l \uparrow^1 W$$

$$\text{(ee)} \quad L \vdash (\textcircled{c}U).T \mapsto_e U$$

### 3. Defining $\lambda\delta$ -2B (2 of 3)

**Parallel rt-transition** with  $n$  t-steps.  $L \vdash T_1 \Rightarrow_n T_2$  [depends on  $h$ ].

$$\begin{array}{c}
 \frac{}{L \vdash \star | \#i \Rightarrow_0 \star | \#i} \text{1R} \quad \frac{K \vdash \#i \Rightarrow_n T}{K.(\Lambda | \Delta W) \vdash \# \uparrow i \Rightarrow_n \uparrow^1 T} \text{1L} \\
 \\
 \frac{K \vdash W_1 \Rightarrow_0 W_2 \quad K.(\Lambda | \Delta W_1) \vdash T_1 \Rightarrow_n T_2}{K \vdash (\lambda | \delta W_1).T_1 \Rightarrow_n (\lambda | \delta W_2).T_2} \text{1B} \\
 \\
 \frac{L \vdash V_1 \Rightarrow_0 V_2 \quad L \vdash T_1 \Rightarrow_n T_2}{L \vdash (@V_1).T_1 \Rightarrow_n (@V_2).T_2} \text{1A} \quad \frac{L \vdash U_1 \Rightarrow_n U_2 \quad L \vdash T_1 \Rightarrow_n T_2}{L \vdash (@U_1).T_1 \Rightarrow_n (@U_2).T_2} \text{1K} \\
 \\
 \frac{L \vdash V_1 \Rightarrow_0 V_2, L \vdash W_1 \Rightarrow_0 W_2, L \vdash T_1 \Rightarrow_n T_2}{L \vdash (@V_1).(\lambda W_1).T_1 \Rightarrow_n (\delta(@W_2).V_2).T_2} \text{1}\beta \quad \frac{L \vdash V_1 \Rightarrow_0 V_2, L \vdash W_1 \Rightarrow_0 W_2, L \vdash T_1 \Rightarrow_n T_2}{L \vdash (@V_1).(\delta W_1).T_1 \Rightarrow_n (\delta W_2).(@ \uparrow^1 V_2).T_2} \text{1}\theta \\
 \\
 \frac{K \vdash W_1 \Rightarrow_n W_2}{K.(\Delta W_1) \vdash \#1 \Rightarrow_n \uparrow^1 W_2} \text{1}\delta \quad \frac{K \vdash T_1 \Rightarrow_n T_2}{K \vdash (\delta W).\uparrow^1 T_1 \Rightarrow_n T_2} \text{1}\zeta \quad \frac{K \vdash T_1 \Rightarrow_n T_2}{K \vdash (@U).T_1 \Rightarrow_n T_2} \text{1}\epsilon \\
 \\
 \frac{}{L \vdash \star s \Rightarrow_1 \star \uparrow_{hs}} \text{1}s \quad \frac{K \vdash W_1 \Rightarrow_n W_2}{K.(\Lambda W_1) \vdash \#1 \Rightarrow_{\uparrow n} \uparrow^1 W_2} \text{1}l \quad \frac{K \vdash U_1 \Rightarrow_n U_2}{K \vdash (@U_1).T \Rightarrow_{\uparrow n} U_2} \text{1}e
 \end{array}$$

This is fully parallel and substitution is linear in a weak head transition.

**Parallel rt-computation** with  $n$  t-steps.  $L \vdash T_1 \Rightarrow_n^* T_2$  [trans. closure].

$$\frac{L \vdash T_1 \Rightarrow_n T_2}{L \vdash T_1 \Rightarrow_n^* T_2} \text{2R} \quad \frac{L \vdash T_1 \Rightarrow_{n_1}^* T \quad L \vdash T \Rightarrow_{n_2}^* T_2}{L \vdash T_1 \Rightarrow_{n_1+n_2}^* T_2} \text{2T}$$

## 4. Defining $\lambda\delta$ -2B (3 of 3)

Extended validity (Automath-like)  $L \vdash T !^*$  [depends on  $h$ ].

$$\begin{array}{c}
 \frac{}{L \vdash \star s !^*} \text{3S} \quad \frac{K \vdash W !^*}{K.(\Lambda|\Delta W) \vdash \#1 !^*} \text{3U} \quad \frac{K \vdash \#i !^*}{K.(\Lambda|\Delta W) \vdash \#\uparrow i !^*} \text{3L} \\
 \\
 \frac{K \vdash W !^* \quad K.(\Lambda|\Delta W) \vdash T !^*}{K \vdash (\lambda|\delta W).T !^*} \text{3B} \\
 \\
 \frac{L \vdash W !^* \quad L \vdash T !^* \quad L \vdash W \Rightarrow_0^* U \quad L \vdash T \Rightarrow_1^* U}{L \vdash (\odot W).T !^*} \text{3K} \\
 \\
 \frac{L \vdash V !^* \quad L \vdash T !^* \quad L \vdash V \Rightarrow_1^* W \quad L \vdash T \Rightarrow_n^* (\lambda W).U}{L \vdash (@V).T !^*} \text{3A}
 \end{array}$$

Notice that in rule 3A we can choose the value of  $n$  at will (0 is OK).

Extended type  $L \vdash T :^* U$  by def.  $L \vdash (\odot U).T !^*$  [depends on  $h$ ].

Restricted validity (PTS-like)  $L \vdash T !$  [depends on  $h$ ].

Rules 4 are like rules 3 above except for rule 4A that is as follows:

$$\frac{L \vdash V ! \quad L \vdash T ! \quad L \vdash V \Rightarrow_1^* W \quad L \vdash T \Rightarrow_1^* (\lambda W).U}{L \vdash (@V).T !} \text{4A}$$

Restricted type  $L \vdash T : U$  by def.  $L \vdash (\odot U).T !$  [depends on  $h$ ].

## 5. Arity assignment and strong normalization

Strong normalization holds for **unbound rt-computation**  $L \vdash T_1 \Rightarrow^* T_2$ , which we define like  $L \vdash T_1 \Rightarrow_n^* T_2$  without the bound  $n$  on all its rules.

Due to rule 1s, we must take terms up to the next **equivalence relation**:

$$\frac{}{\star s_1 \doteq \star s_2} 5S \quad \frac{}{\#i \doteq \#i} 5R \quad \frac{U_1 \doteq U_2 \quad T_1 \doteq T_2}{(\lambda|\delta|@|\odot U_1).T_1 \doteq (\lambda|\delta|@|\odot U_2).T_2} 5P$$

We define inductively **strongly normalizing terms** with the next rule:

$$\frac{(\forall T_2) L \vdash T_1 \Rightarrow T_2 \supset (T_1 \doteq T_2 \supset \perp) \supset L \vdash \Rightarrow^* \text{SN}(T_2)}{L \vdash \Rightarrow^* \text{SN}(T_1)} \text{rt-sn}$$

**Strong normalization** follows from:  $L \vdash T \text{ !}^*$  implies  $(\exists A) L \vdash T : A$  according to the next simple type assignment with one base type  $\star$ .

$$\frac{}{L \vdash \star s : \star} 6S \quad \frac{K \vdash \#i : A}{K.(\Lambda|\Delta W) \vdash \#\uparrow i : A} 6L \quad \frac{K \vdash W : B}{K.(\Lambda|\Delta W) \vdash \#1 : B} 6U \quad \frac{L \vdash V : B, L \vdash T : B \rightarrow A}{L \vdash (@V).T : A} 6A$$

$$\frac{K \vdash W : B, K.(\Lambda W) \vdash T : A}{K \vdash (\lambda W).T : B \rightarrow A} 6Y \quad \frac{K \vdash W : B, K.(\Delta W) \vdash T : A}{K \vdash (\delta W).T : A} 6D \quad \frac{L \vdash W : A, L \vdash T : A}{L \vdash (\odot W).T : A} 6K$$

Notice that we can set the expressive power of  $\lambda\delta$ -2B at the level of  $\lambda \rightarrow$ .

## 6. Transition in environment and big-tree theorem

Parallel r-transition in environment is:  $\frac{}{\star \Rightarrow_0 \star} 7S \quad \frac{K_1 \Rightarrow_0 K_2 \quad K_1 \vdash W_1 \Rightarrow_0 W_2}{K_1.(\Lambda|\Delta W_1) \Rightarrow_0 K_2.(\Lambda|\Delta W_2)} 7B$

Structural induction on a closure  $[L, T]$  relies on  $[L_1, T_1] \sqsupset [L_2, T_2]$  (s-step), whose transitive closure  $[L_1, T_1] \sqsupset^+ [L_2, T_2]$  is well founded.

$$\frac{}{[K.(\Lambda|\Delta W), \#1] \sqsupset [K, W]} 8U \quad \frac{}{[K.(\Lambda|\Delta W), \uparrow^1 T] \sqsupset [K, T]} 8L \quad \frac{}{[L, (@|\odot V).T] \sqsupset [L, T]} 8F$$

$$\frac{}{[L, (\lambda|\delta|@|\odot V).T] \sqsupset [L, V]} 8P \quad \frac{}{[L, (\lambda|\delta W).T] \sqsupset [L.(\Lambda|\Delta W), T]} 8B$$

Big-tree induction on a valid closure relies on  $[L_1, T_1] \succ [L_2, T_2]$  (rst-step), whose transitive closure  $[L_1, T_1] \succ^+ [L_2, T_2]$  is well founded.

$$\frac{[L_1, T_1] \sqsupset [L_2, T_2]}{[L_1, T_1] \succ [L_2, T_2]} 9R1 \quad \frac{L \vdash T_1 \Rightarrow T_2 \quad T_1 \stackrel{\neq}{=} T_2 \sqsupset \perp}{[L, T_1] \succ [L, T_2]} 9R2$$

In particular we define inductively **well-founded closures** with the rule:

$$\frac{(\forall L_2, T_2) [L_1, T_1] \succ [L_2, T_2] \sqsupset \text{>SN}(L_2, T_2)}{\text{>SN}(L_1, T_1)} \text{rst-sn}$$

An induction principle originates from the **big-tree theorem** stating that:

$$L \vdash T : A \text{ (and thus } L \vdash T !^*) \text{ implies } \text{>SN}(L, T).$$

## 7. Confluence and preservation

With the next rules we define the building blocks for the confluence of rt-computation and the preservation of validity through rt-computation:

$$\begin{array}{c}
 \frac{L_0 \vdash T_0 \Rightarrow_0 T_1 \quad L_0 \vdash T_0 \Rightarrow_0 T_2 \quad L_0 \Rightarrow_0 L_1 \quad L_0 \Rightarrow_0 L_2}{(\exists T) L_1 \vdash T_1 \Rightarrow_0 T \ \& \ L_2 \vdash T_2 \Rightarrow_0 T} \mathbf{D}(L_0, T_0) \\
 \\
 \frac{L_0 \vdash T_0 !^* \quad L_0 \vdash T_0 \Rightarrow_{n_1} T_1 \quad L_0 \vdash T_0 \Rightarrow_{n_2} T_2 \quad L_0 \Rightarrow_0 L_1 \quad L_0 \Rightarrow_0 L_2}{(\exists T) L_1 \vdash T_1 \Rightarrow_{n_2-n_1}^* T \ \& \ L_2 \vdash T_2 \Rightarrow_{n_1-n_2}^* T} \mathbf{K}(L_0, T_0) \\
 \\
 \frac{L_0 \vdash T_0 !^* \quad L_0 \vdash T_0 \Rightarrow_{n_1}^* T_1 \quad L_0 \vdash T_0 \Rightarrow_{n_2}^* T_2 \quad L_0 \Rightarrow_0 L_1 \quad L_0 \Rightarrow_0 L_2}{(\exists T) L_1 \vdash T_1 \Rightarrow_{n_2-n_1}^* T \ \& \ L_2 \vdash T_2 \Rightarrow_{n_1-n_2}^* T} \mathbf{C}(L_0, T_0) \\
 \\
 \frac{L_0 \vdash T_0 !^* \quad L_0 \vdash T_0 \Rightarrow_n T_1 \quad L_0 \Rightarrow_0 L_1}{L_1 \vdash T_1 !^*} \mathbf{P}(L_0, T_0)
 \end{array}$$

Validity makes the pair  $(\epsilon, e)$  confluent producing the kite  $\mathbf{K}(L_0, T_0)$ .

The rules  $\mathbf{C}(L_0, T_0)$ ,  $\mathbf{P}(L_0, T_0)$  are mutually dependent and we have:

$$\begin{array}{c}
 \frac{(\forall L_0, T_0) [L, T] \sqsupset^+ [L_0, T_0] \supset \mathbf{D}(L_0, T_0)}{\mathbf{D}(L, T)} \text{Th1}(L, T) \\
 \\
 \frac{(\forall L_0, T_0) [L, T] > [L_0, T_0] \supset \mathbf{C}(L_0, T_0) \ \& \ \mathbf{P}(L_0, T_0)}{\mathbf{K}(L, T) \ \& \ \mathbf{C}(L, T) \ \& \ \mathbf{P}(L, T)} \text{Th2}(L, T)
 \end{array}$$

$\mathbf{D}(L, T)$  is immediate, the big-tree induction yields  $\mathbf{C}(L, T) \ \& \ \mathbf{P}(L, T)$ .

## 8. Convertibility and derived type rules

We define **contextual convertibility**  $L \vdash U_1 \Leftrightarrow_{0,0}^* U_2$  with the next rules:

$$\frac{L \vdash U_1 \Rightarrow_0 U_2}{L \vdash U_1 \Leftrightarrow_{0,0}^* U_2} 10R \quad \frac{L \vdash U_2 \Rightarrow_0 U_1}{L \vdash U_1 \Leftrightarrow_{0,0}^* U_2} 10X \quad \frac{L \vdash U_1 \Leftrightarrow_{0,0}^* U \quad L \vdash U \Leftrightarrow_{0,0}^* U_2}{L \vdash U_1 \Leftrightarrow_{0,0}^* U_2} 10T$$

We obtain the **restricted type** rules from  $L \vdash T ! \text{ iff } (\exists U) L \vdash T : U$

$$\frac{K \vdash V : W}{K.(\Delta V) \vdash \#1 : \uparrow^1 W} 11\Delta \quad \frac{K \vdash W !}{K.(\Lambda W) \vdash \#1 : \uparrow^1 W} 11\Lambda \quad \frac{K \vdash \#i : L}{K.(\Lambda|\Delta V) \vdash \#\uparrow i : \uparrow^1 U} 11L$$

$$\frac{}{L \vdash \star s : \star \uparrow_h s} 11S \quad \frac{K \vdash V ! \quad K.(\Lambda|\Delta V) \vdash T : U}{K \vdash (\lambda|\delta V).T : (\lambda|\delta V).U} 11B \quad \frac{L \vdash T : U}{L \vdash (\odot U).T : U} 11K$$

$$\frac{L \vdash V : W \quad L \vdash T : (\lambda W).U}{L \vdash (@V).T : (@V).(\lambda W).U} 11A \quad \frac{L \vdash T : U_1 \quad L \vdash U_1 \Leftrightarrow_{0,0}^* U_2 \quad L \vdash U_2 !}{L \vdash T : U_2} 11C$$

We obtain the **extended type** rules from  $L \vdash T !^* \text{ iff } (\exists U) L \vdash T :^* U$ .

Rules 12 are like rules 11 above except for rule 11A that is replaced by:

$$\frac{K \vdash V :^* W \quad K.(\Lambda W) \vdash T :^* U}{K \vdash (@V).(\lambda W).T :^* (@V).(\lambda W).U} 12A1 \quad \frac{L \vdash T :^* U \quad L \vdash (@V).U !^*}{L \vdash (@V).T :^* (@V).U} 12A2$$

As of now we can confirm the next main invariants: correctness of types, uniqueness of types up to conversion, **preservation of types by reduction**.

## 9. Comments and future work

The **current specification** of  $\lambda\delta$ -2B in Matita consists of the following:

Branch	Definitions	Propositions	Loss factor
Additions to the library	148	781	2.2
Structures for the $\lambda\delta$ family	122	868	4.0
Specific structures for $\lambda\delta$ -2B	41	854	4.6

We developed this specification in three years (Oct. 2015 to Nov. 2018).

W.r.t.  $\lambda\delta$ -2A, the present specification stands **without the next notions**:

- **canonical typing** of a term (replaced by rt-transition with one t-step);
- **degree** of a term (we proved preservation w/o induction on the degree).

We are working on the remaining properties of  $\lambda\delta$ -1A, esp. **decidability**;

on linking the ext. and rest. type systems via **formal  $\eta$ -conversion on  $\lambda$** ;

on  $\lambda\delta$ -2B **denotational semantics** (first step: define what a model is).

**Thank you**